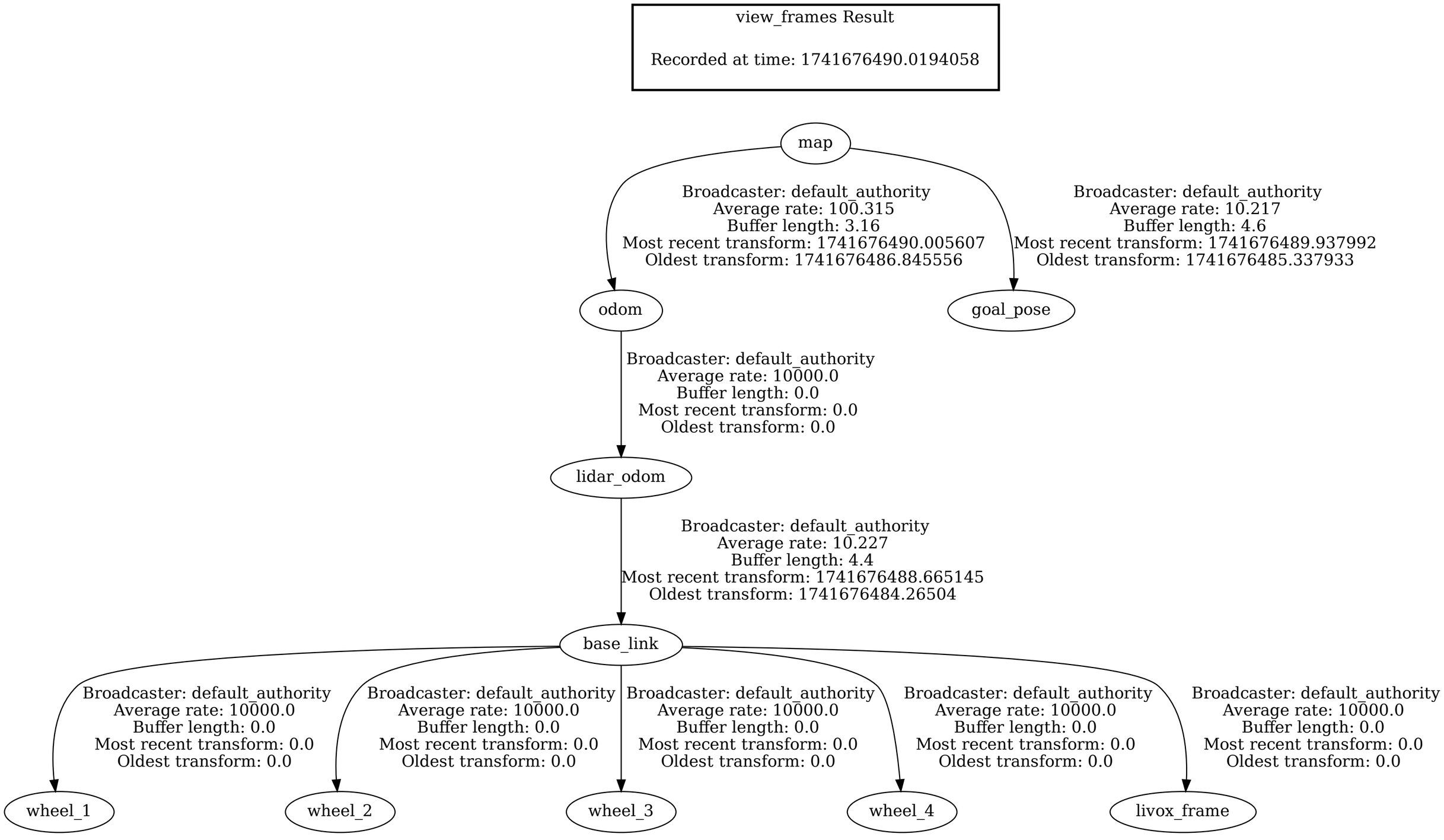
view_frames Result
Recorded at time: 1741676490.0194058
map
Broadcaster: default_authority
Average rate: 100.315
Buffer length: 3.16
Most recent transform: 1741676490.005607
Oldest transform: 1741676486.845556
Broadcaster: default_authority
Average rate: 10.217
Buffer length: 4.6
Most recent transform: 1741676489.937992
Oldest transform: 1741676485.337933
odom
goal_pose
Broadcaster: default_authority
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0
lidar_odom
Broadcaster: default_authority
Average rate: 10.227
Buffer length: 4.4
Most recent transform: 1741676488.665145
Oldest transform: 1741676484.26504
base_link
Broadcaster: default_authority
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0
Broadcaster: default_authority
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0
Broadcaster: default_authority
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0
Broadcaster: default_authority
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0
Broadcaster: default_authority
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0
wheel_1
wheel_2
wheel_3
wheel_4
livox_frame